## **PRELIMINARY**

## **Navman Jupiter 30**

# NAVMAN

## Surface mount 20-channel high sensitivity GPS receiver module



Navman's Jupiter 30 has been designed without compromise to give the ultimate in high sensitivity GPS performance at a very competitive price. Jupiter 30 acquires GPS position faster under low signal conditions than other available GPS engines. Tracking continues in areas of dense foliage or built-up inner city environments and even indoors down to –159 dBm.

Using the new and highly integrated GSC3 from SiRF and carefully selected key components including TCXO, LNA and Flash, the Jupiter 30 offers faster GPS acquisition, up to 10% lower power consumption, a wider operating voltage range and greater noise rejection capability than leading competitors products using a similar architecture.

Sharing the same form factor and extended software messaging as the Jupiter 20, the Jupiter 30 offers a risk free upgrade path for any customer, using an active or passive antenna.

## **Key Features**

- ultra-high sensitivity GPS receiver
- · faster times to fix under all conditions
- · indoor fixes and tracking capability
- SIRFLoc multi-mode GPS support for improved fix availability
- 20 GPS channels supported
- 200,000+ effective correlators
- 0.5PPM TXCO for optimal performance
- integral switching LNA
- on-board Flash
- ARM 7CPU
- SBAS enabled
- RoHS compliant
- 3 V low power operation

#### Jupiter 30 architecture main OR-ing battery power circuit power active or passive antenna VDD\_RTC\_SRAM brown-out regulator detector regulator LNA switch SRESET LNA EN VCC RF VDD BB VDD RC TCXO XTAL IN GSC3f-7879 (or GSC3 no flash) attenuator/ RFIN LNA saw filter UART RTC crystal controls/ #RST AD [0-19] D [0-15] CTRL **GPIO** ports 4-16 Mb Flash/ 8 Mb standard optional

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## **Product specifications**

#### Receiver architecture

- 20-channel, 200 000 effective correlators, L1 1575.42 MHz
- C/A code (1.023 MHz chip rate)
- code-plus-carrier tracking (carrier-aided tracking)
- velocity, up to 500 m/s
- acceleration, up to 5 G

### Tracking capability

• 20 satellites simultaneously

### **Accuracy**

- horizontal accuracy: better than 2.1 m (CEP),
  5.2 m (2 dRMS)
- PPS accuracy: typically better than 1 µs

## Acquisition/re-acquisition performance

Mode	@ -125 dB	
	95%	Typical
hot start TTFF	<1s	500 ms
warm start TTFF	38 s	32s
cold start TTFF	42s	34 s

Mode	@ -140dB		
	95%	Typical	
hot start TTFF	<1	<1	
warm start TTFF	59 s	49 s	
cold start TTFF	66 s	52 s	

#### **Antenna input**

- · integral LNA for use with passive antenna
- active antenna powered through receiver (100 mA max at 12 VDC max)

#### **Datums**

• 5 user defined, default: WGS-84

## **Environmental**

- $\bullet$  operating temperature:  $-40^{\circ}\text{C}$  to  $+85^{\circ}\text{C}$
- humidity: up to 95% non-condensing
- altitude: -305 m to 18000 m

#### **Physical**

- dimensions: 25.4 x 25.4 x 3.0 mm
- weight: 4 g

### **On-board filtering**

- L1 -75 MHz, -30 dB
- L1 +50 MHz, -20 dB

#### **Data interfaces**

- two serial ports available (1 for DGPS input)
- 6 GPIOs controlled by serial command
- CMOS-level (3.3 VDC)
- · selectable baud rates
- selected NMEA-0183/SiRF binary messages: latitude, longitude, elevation, velocity, heading, time, satellite tracking status, command/control messages
- · SiRF binary interface: raw data

#### **Electrical**

- input power range: 3.0 to 3.6 VDC
- · power consumption

Mode	Power consumption		
wode	@3V	@3.3V	
average sustained power (after 1st solution)	<157 mW	<174 mW	
average sustained acquisition power (before 1st solution)	<202 mW	<224 mW	
average initial acquisition power (1.5–2s)	<231 mW	<257 mW	

### Connectors

· data/power/RF through surface mount pads

#### **Related documents**

- Data sheet LA000576-G
- Integrator's manual LA000577-G
- Evaluation kit guide TBC

## **Ordering information**

• TBC

Contact your local distributor or Navman OEM:













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